

# Short Term Traffic Prediction



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# Traffic Data

- Time
- Flow (no. of cars per minute)
- Average Speed (Km per hr)

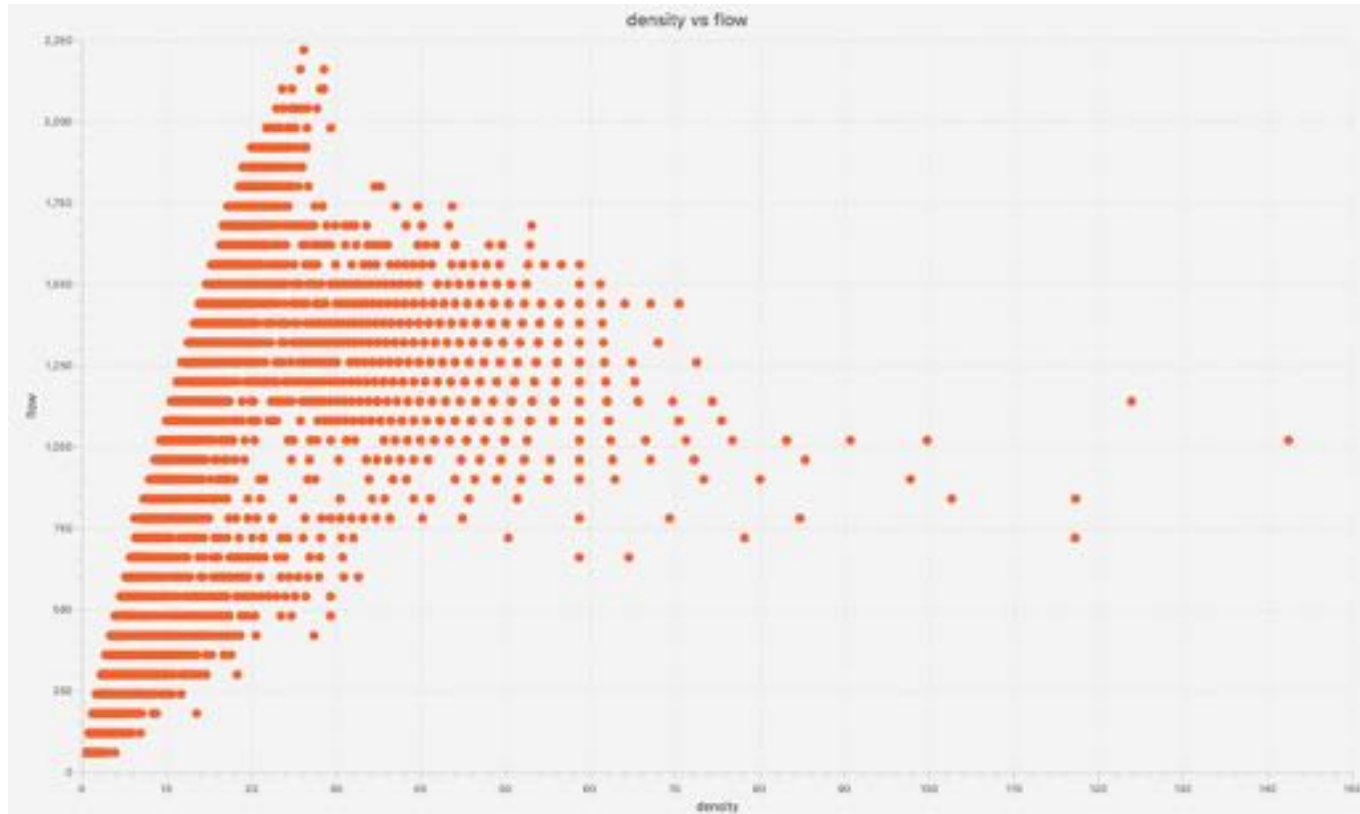


flow / speed = Density (Cars per Km)



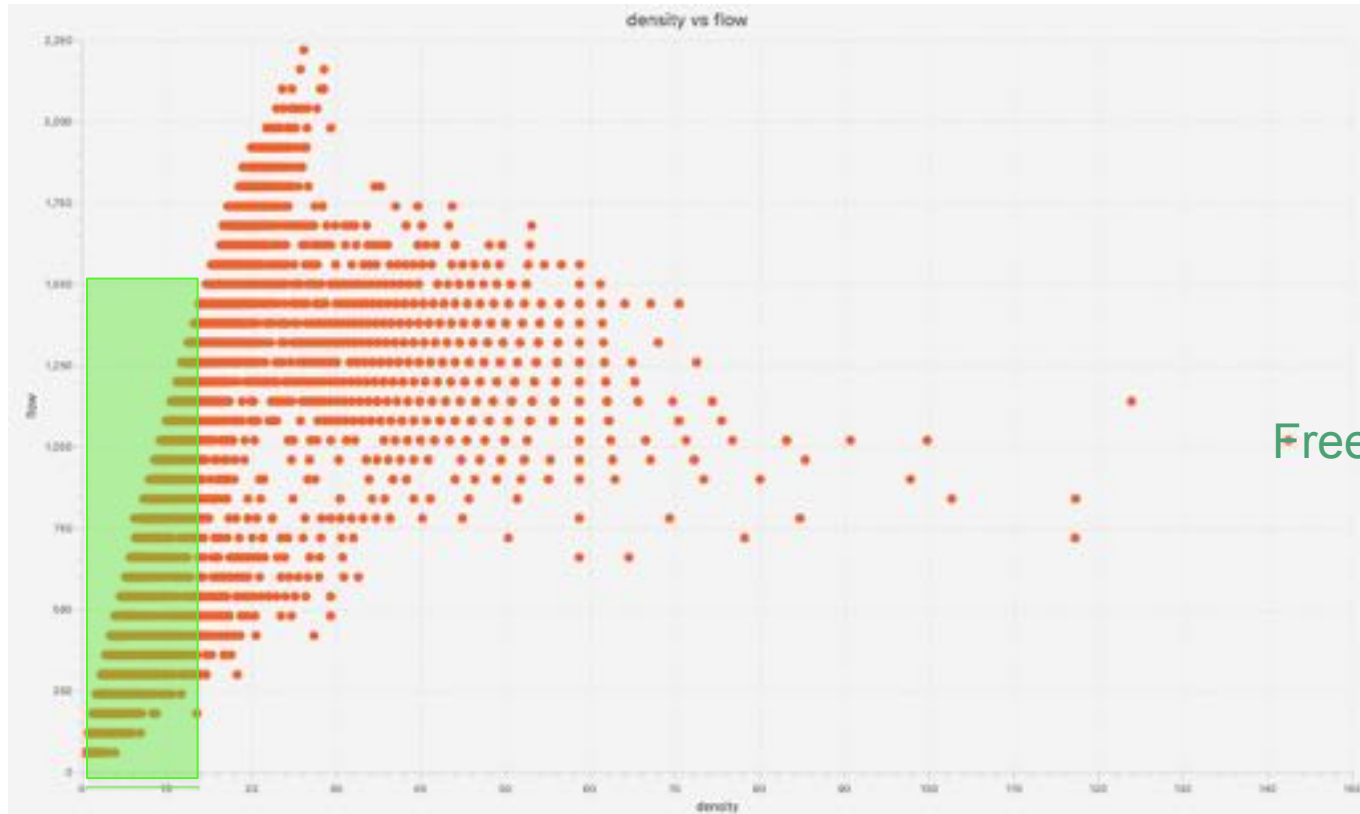
# Traffic Flow Measurements

*Flow*



*Density*

# Traffic Flow Measurements



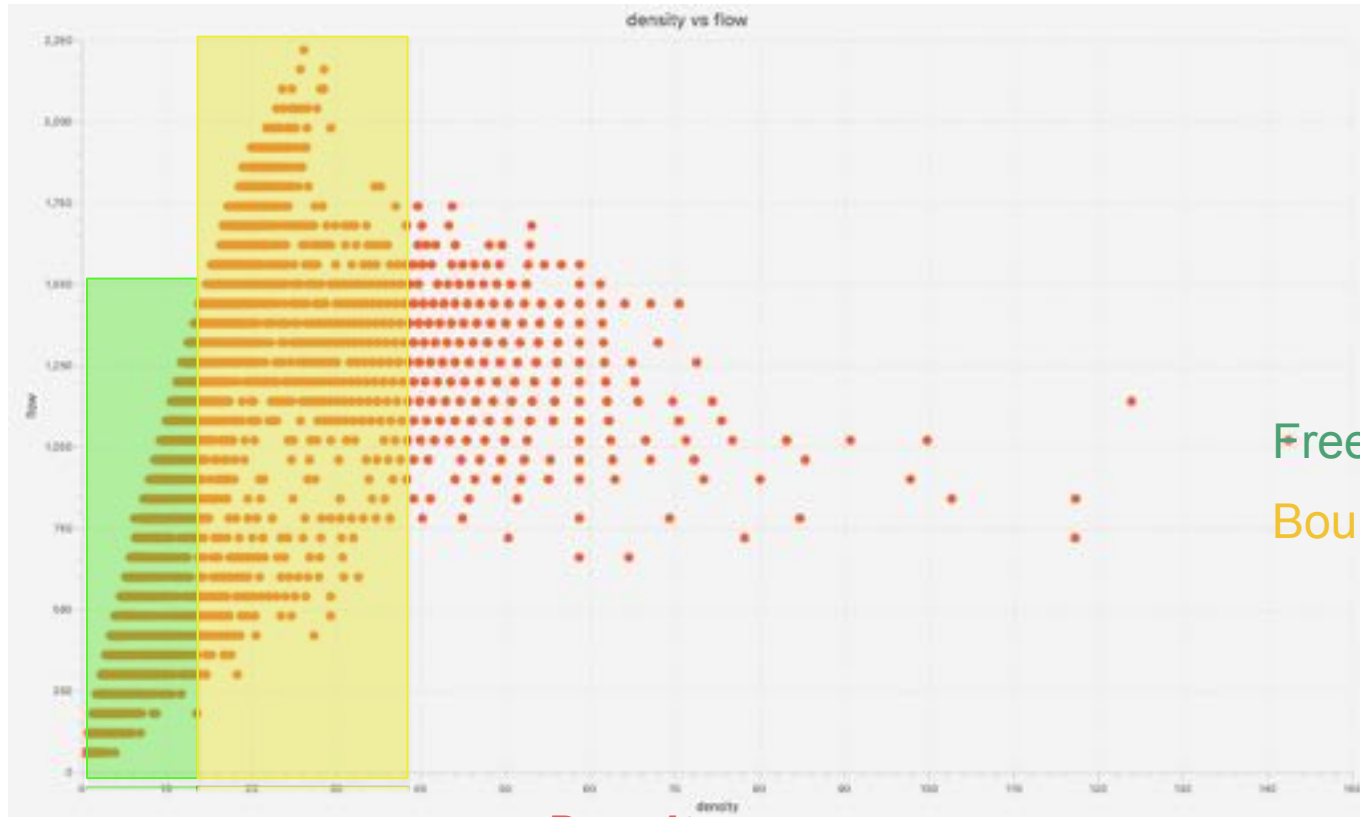
*Flow*

Free flow

*Density*

# Traffic Flow Measurements

*Flow*



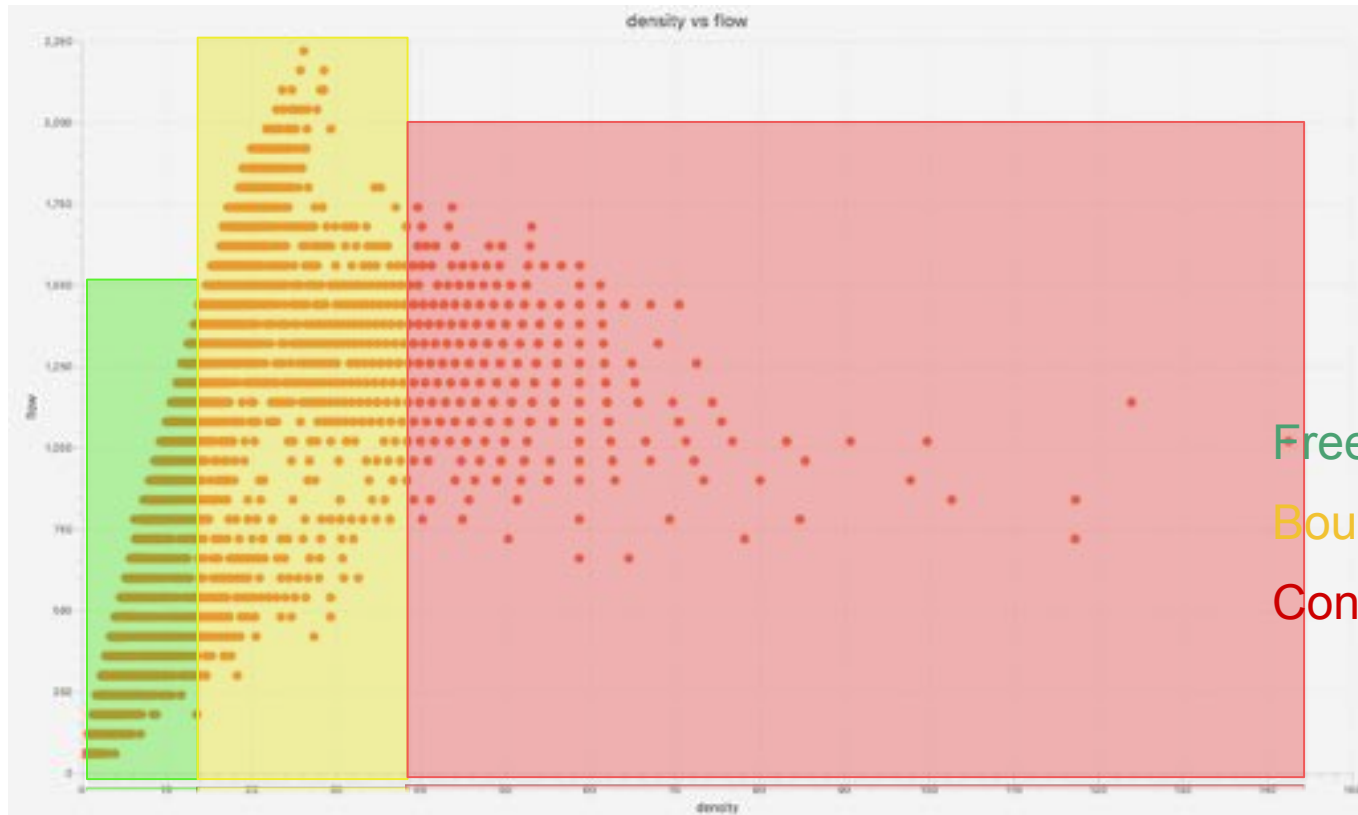
Free flow

Bounded flow

*Density*

# Traffic Flow Measurements

*Flow*



Free flow

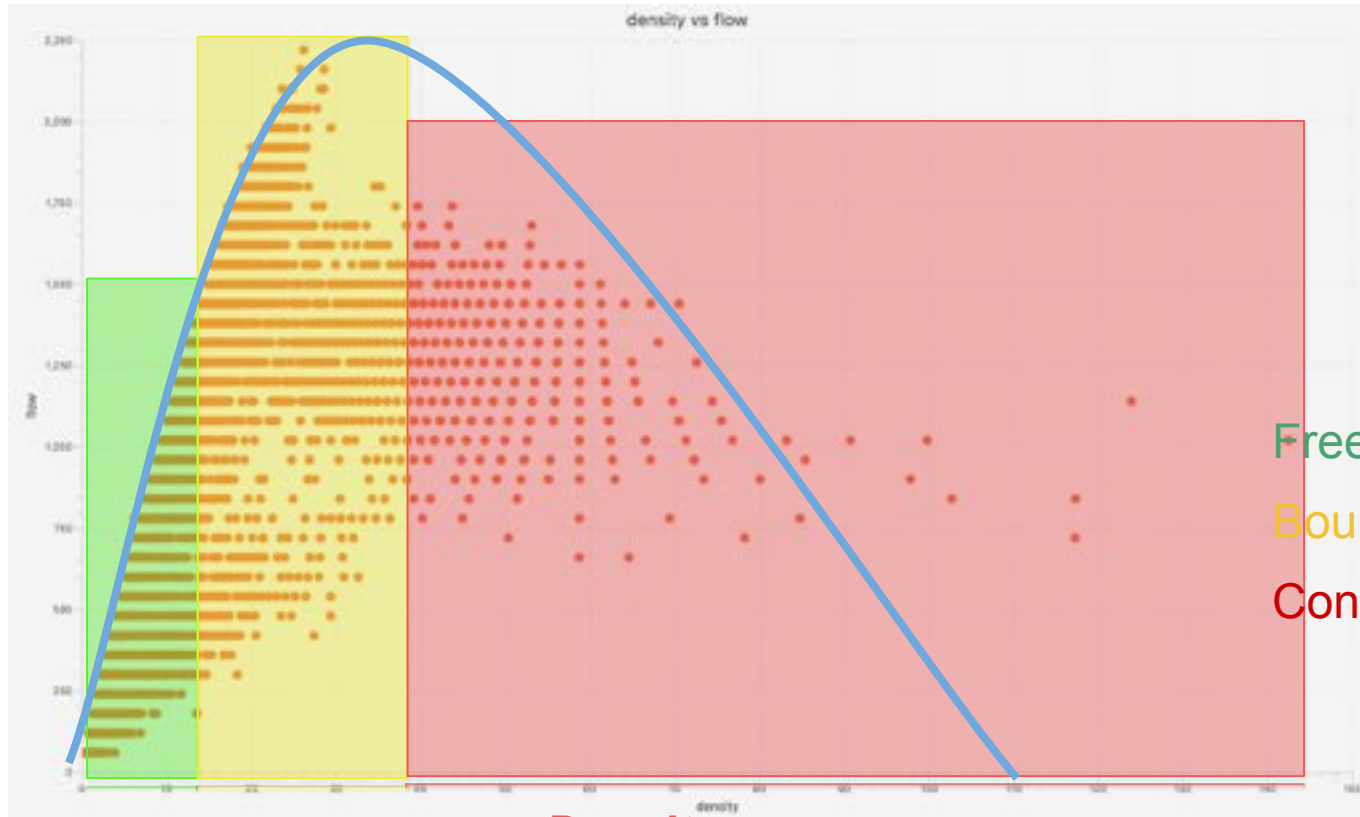
Bounded flow

Congestion

*Density*

# Traffic Flow Theory

*Flow*



Free flow

Bounded flow

Congestion

*Density*

# Prediction

## What happens in the future ?



# Models

- **Time Based:**

- Based on time series of data
- Input data is entered in time series
- Predict the future values in the time series

- **Space and Time Based:**

- Based on placement of the sensors
- Input data (time series) is entered for few sensors
- Predict the values for missing sensors

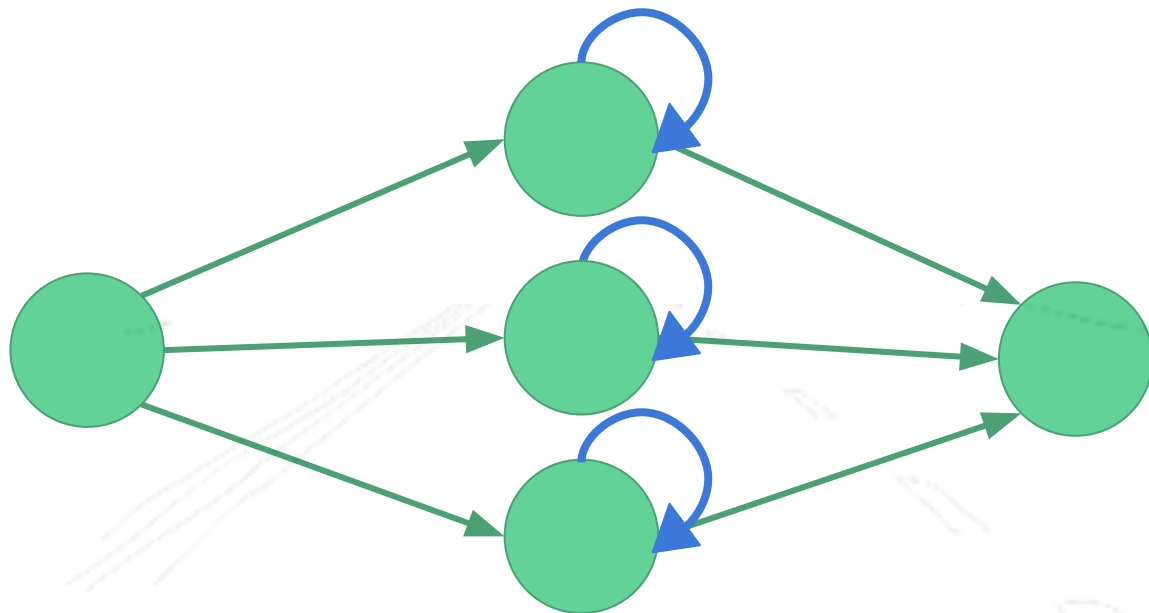
# Technology

- **Keras** machine learning library in python
- RNN recurrent neural networks (**LSTMs**)
- **Stacked** LSTMs



# RNN (Recurrent Neural Networks)

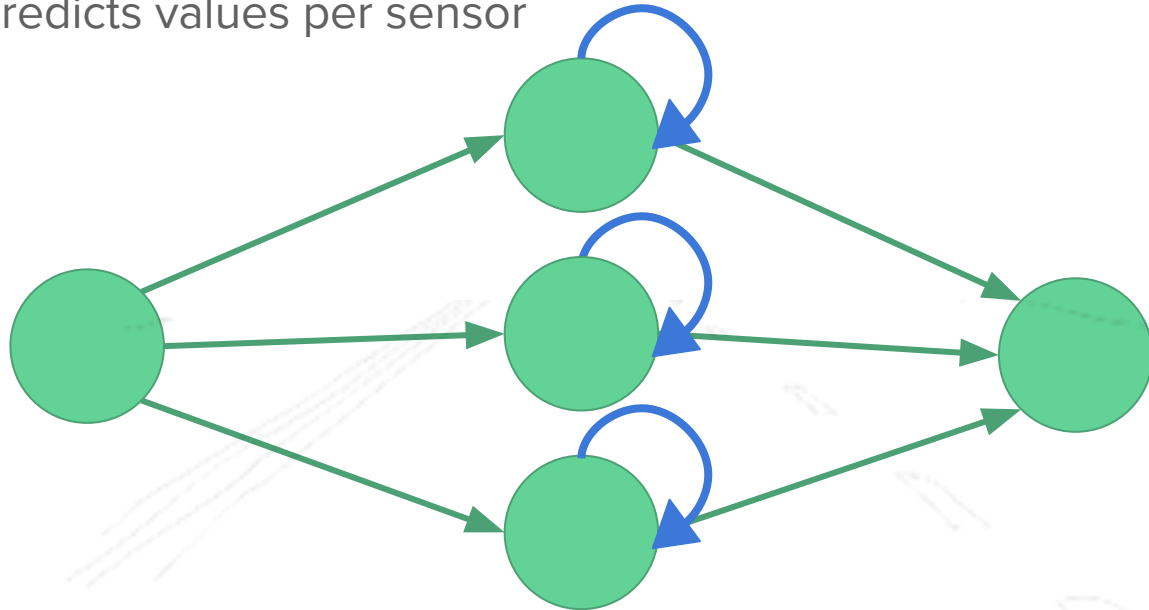
- Good for learning **sequential** data
- Maintains a "**memory**" to keep information about the past using **feedback**.



# Time Based

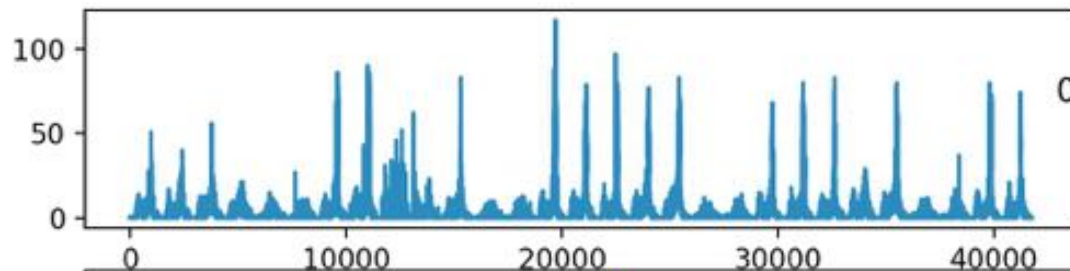
-i

- The model is trained separately for every sensor
- The model predicts values per sensor

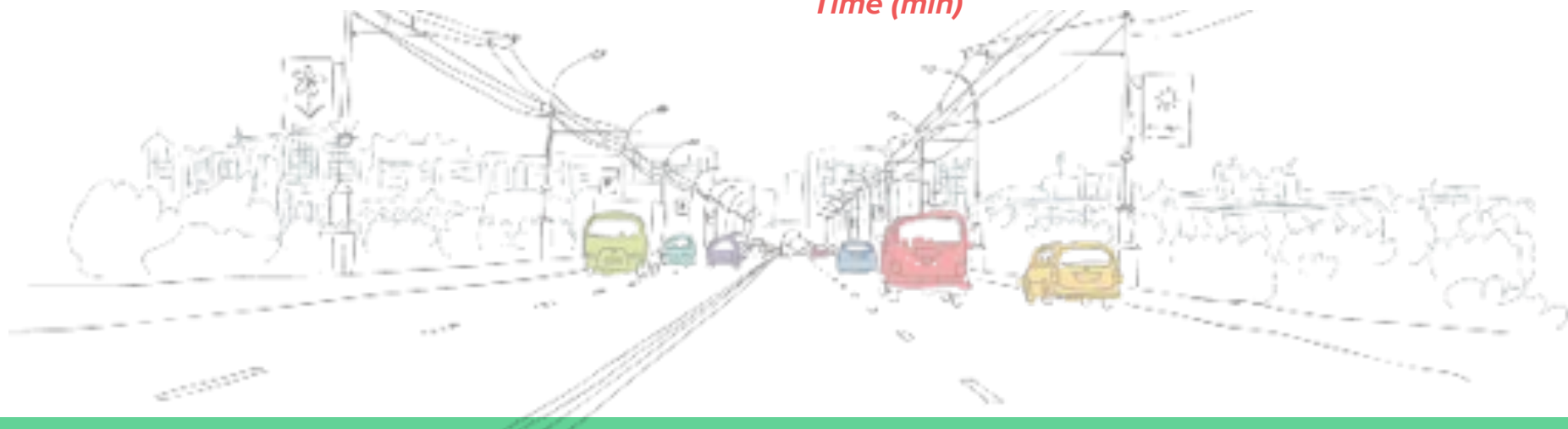


# Input

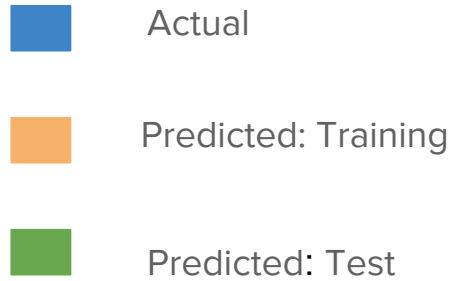
*Density  
(vehicle / km)*



*Time (min)*

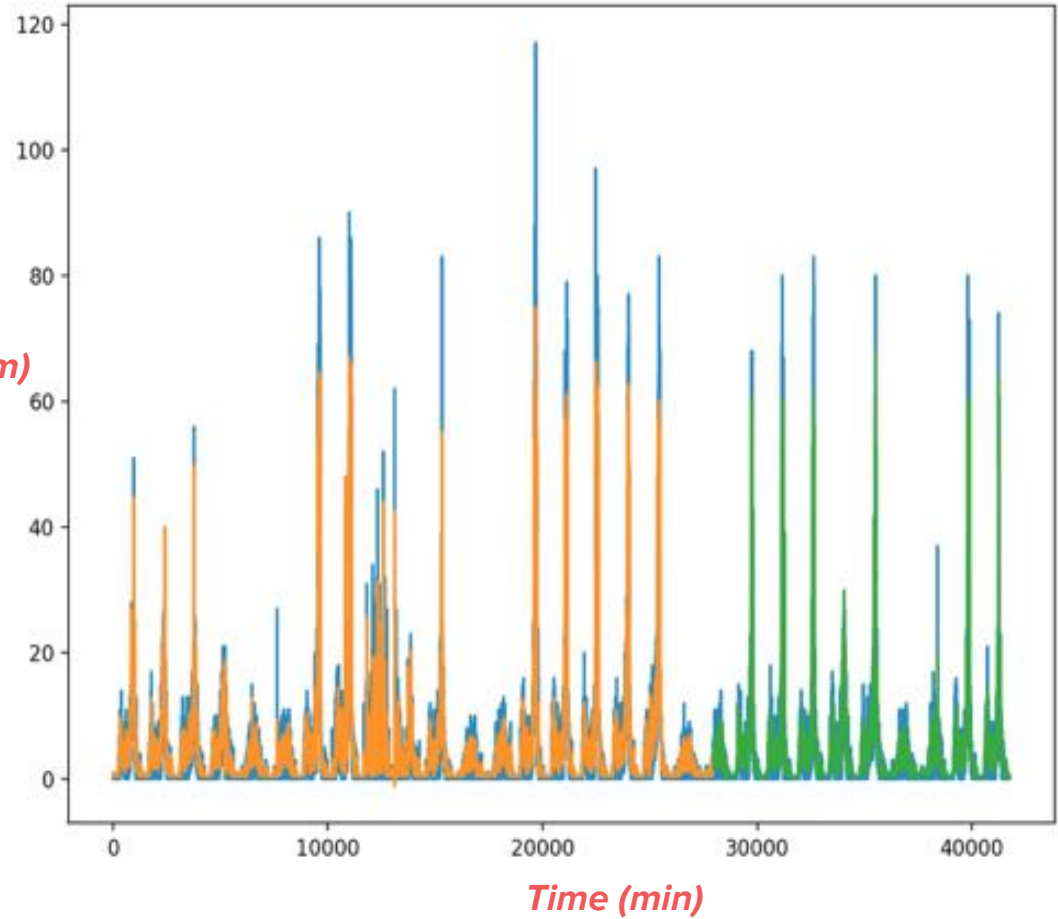


# Prediction



RMSE: 3  
20 min

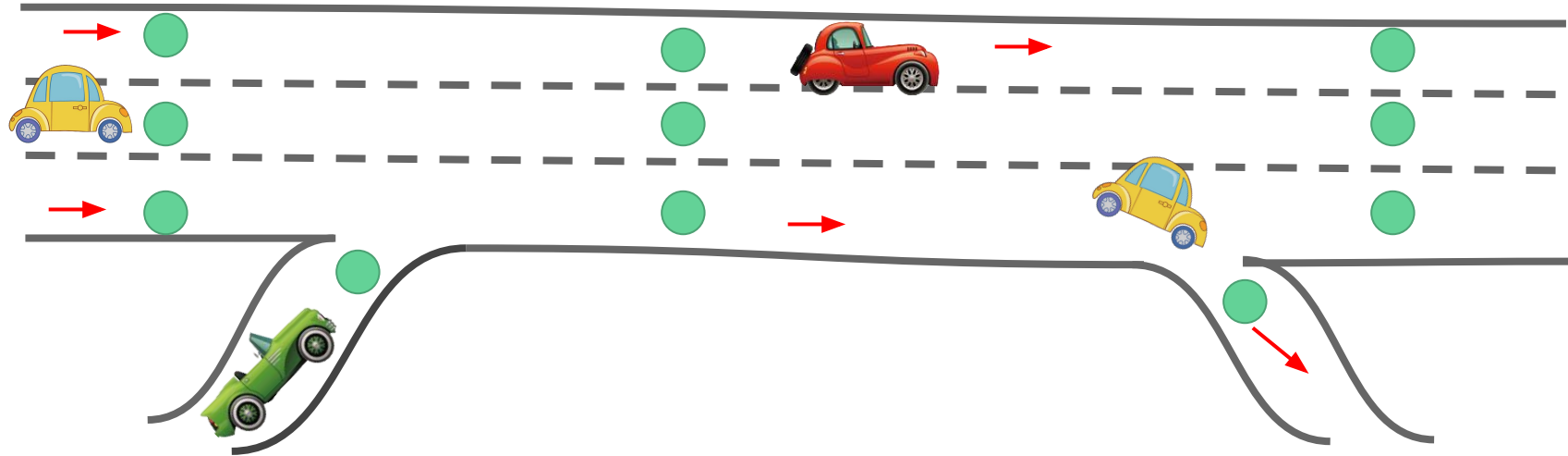
*Density  
(vehicle / km)*



# Time Based

-ii

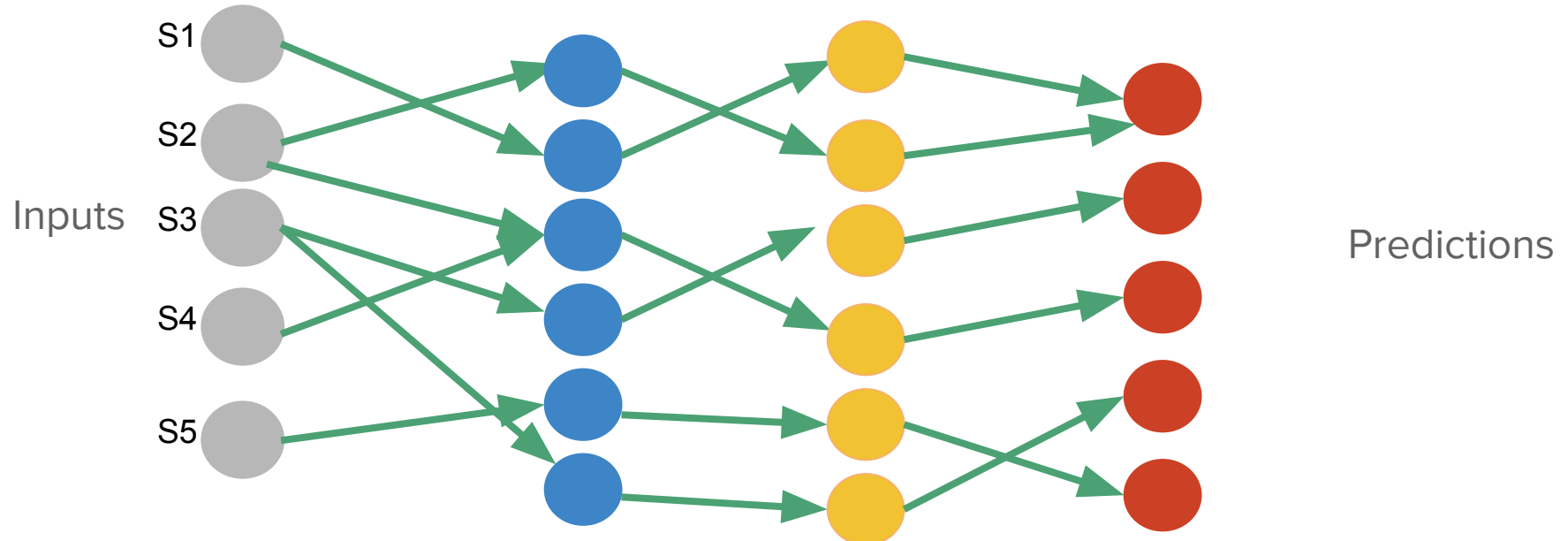
- The model is trained for all the sensors in a road segment
- The model predicts values for all the sensors



# Time Based

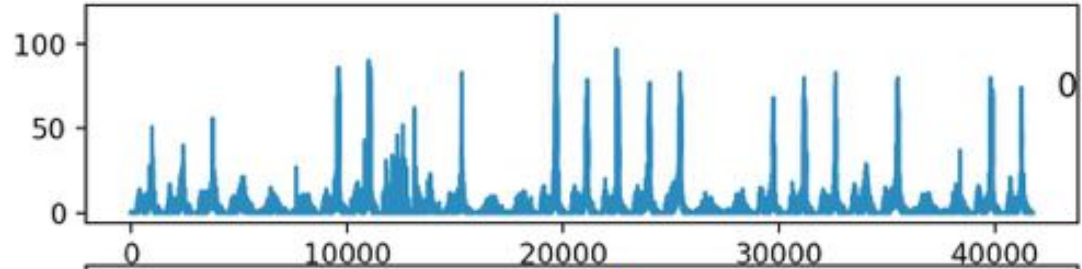
-ii

- The model is trained for all the sensors in a road segment
- The model predicts values for all the sensors



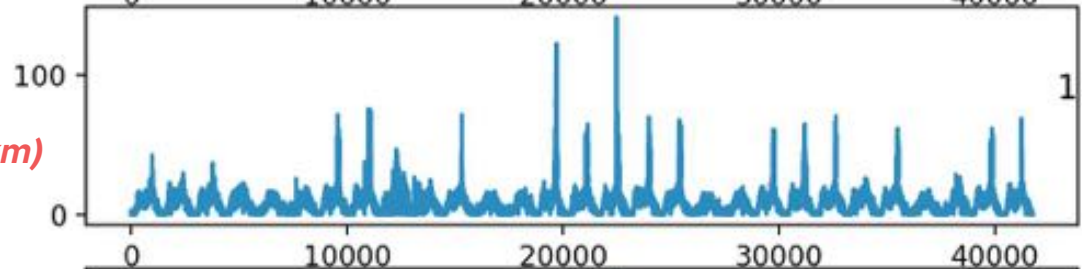
# Time Series

Sensor 1

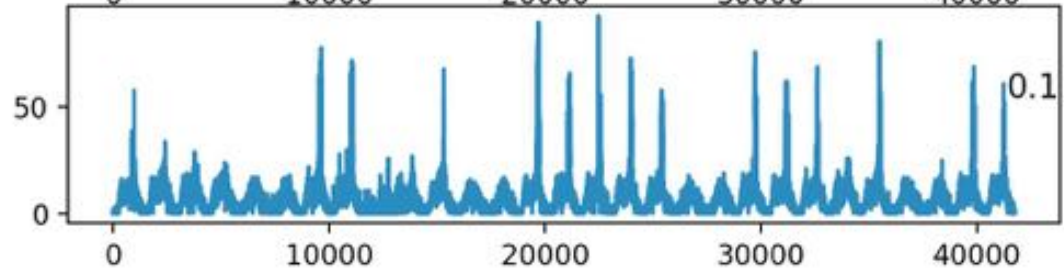


Sensor 2

*Density  
(vehicle / km)*



Sensor 3



*Time (min)*

# Results

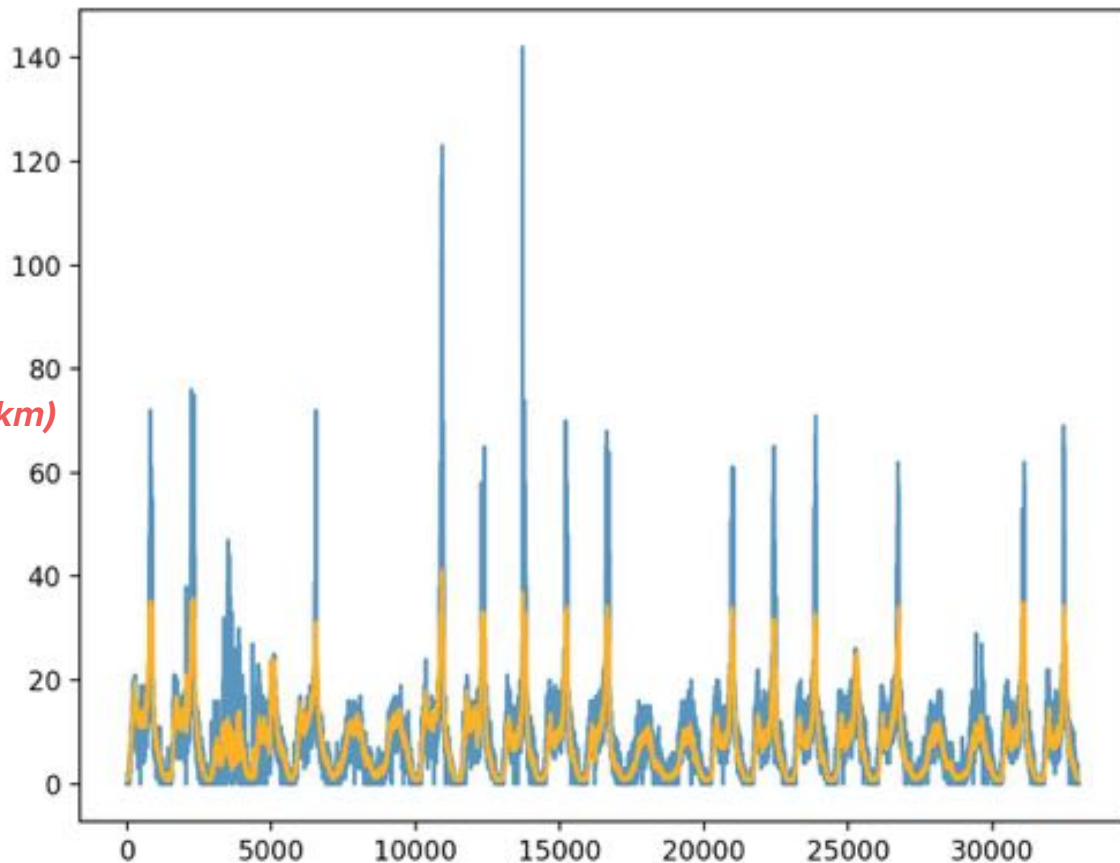


Actual



Predicted

*Density  
(vehicle / km)*

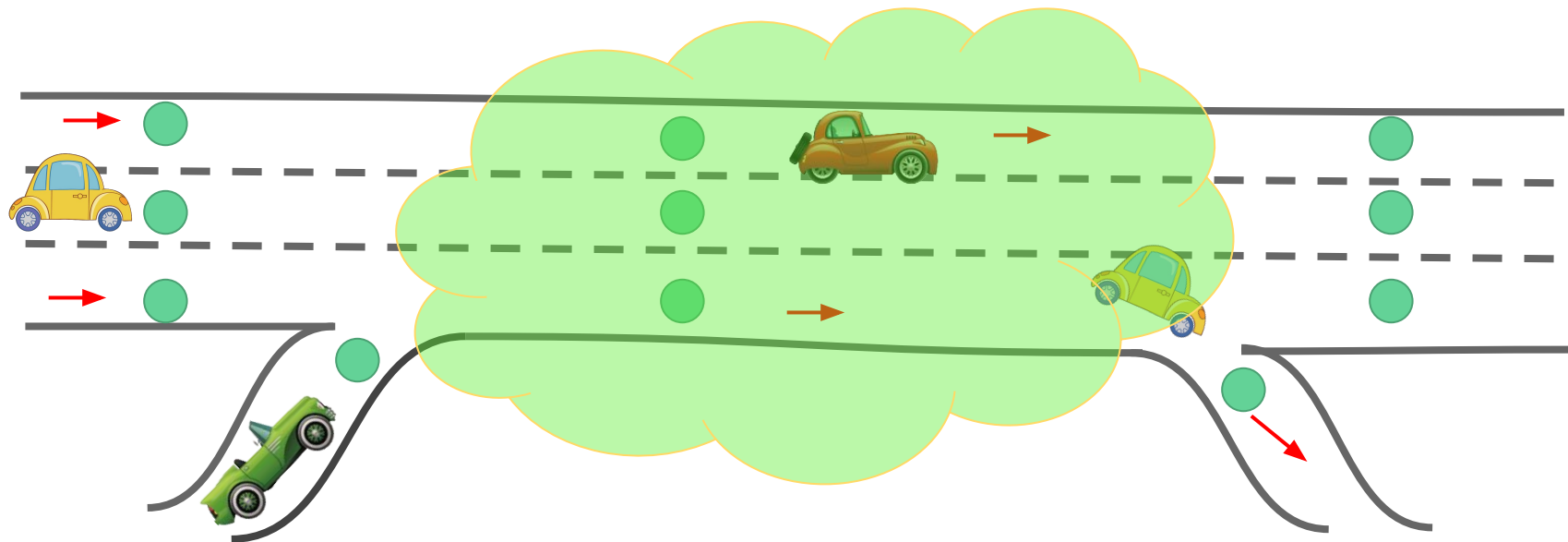


RMSE: 3.25  
20 min

*Time (min)*

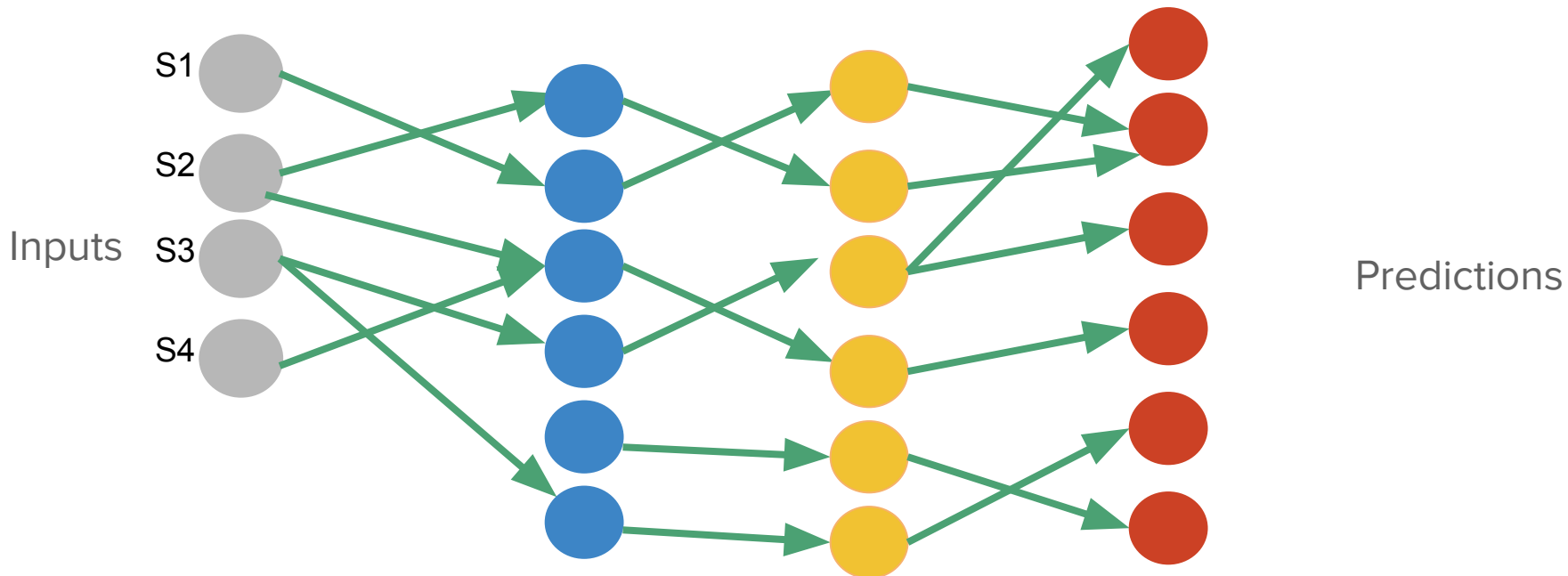
# Space & Time Based

- The model is trained for few sensors in a road segment
- The model predicts values for all the sensors

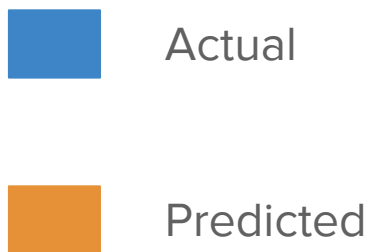


# Space & Time Based

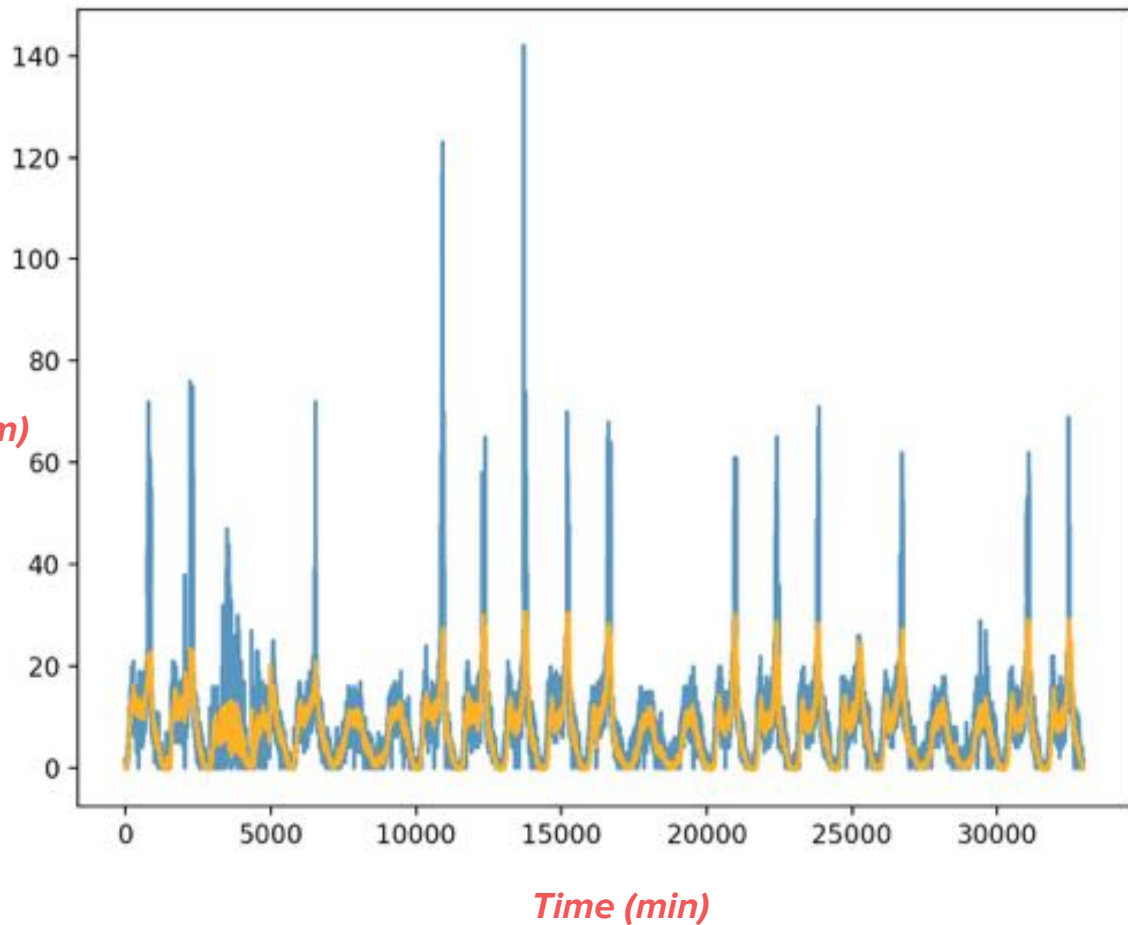
- The model is trained for few sensors in a road segment
- The model predicts values for all the sensors



# Results



*Density  
(vehicle / km)*



RMSE: 5.14  
20 min

# Future Work

- Clustering similar sensors for the time model (i).
- Comparing all different models

